

In the Specification:

Please amend the specification as follows:

Page 10, twelfth paragraph:

Figure 1 is an industrial robot system comprising an industrial robot 1 with a control unit 1a, a manipulator 1b and a robot tool, a spot weld gun 2. The industrial robot comprises a foot 3 mounted to a base 4. The foot supports a stand 5, which is arranged to rotate in relation to the foot 3 about a first axis A. The stand 5 supports a first robot arm 6, arranged to rotate in relation to the stand 5 about a second axis B. The first robot arm supports an arm housing 7, which is arranged to rotate in relation to the first robot ~~arm 5~~ arm 6 about a third axis C. The arm housing 7 supports a second robot arm 8, arranged to rotate in relation to the arm housing 7 about a fourth axis D, and where the fourth axis D coincides with the longitudinal axis of the second robot arm 8. The second robot arm 8 comprises a wrist housing 9, which is supported by a wrist 10. The wrist housing 9 is arranged to rotate about a fifth axis E, which coincides with the longitudinal axis of the wrist. The wrist housing 9 supports a turn disc 11, which is arranged to rotate about a sixth axis F. The turn disc 11 comprises a tool holder 12, which is adapted for attachment of a tool, such as, for example, a spot welding gun 2.